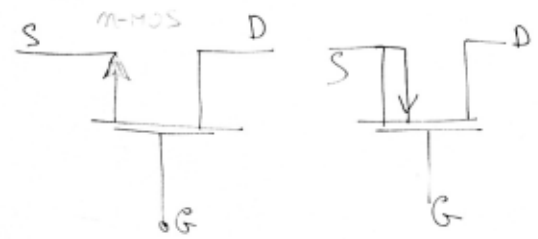
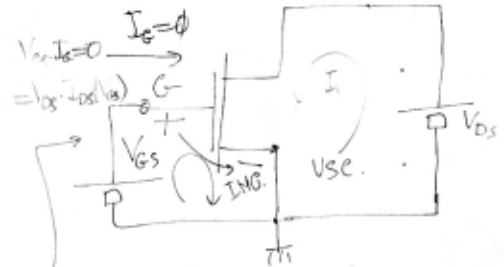
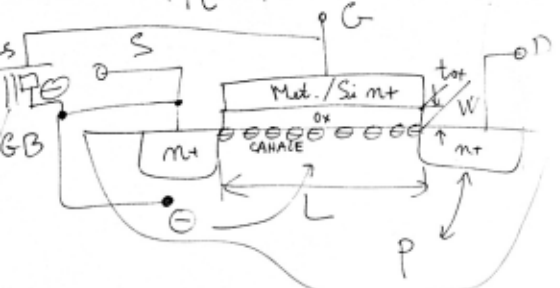


N-MOS

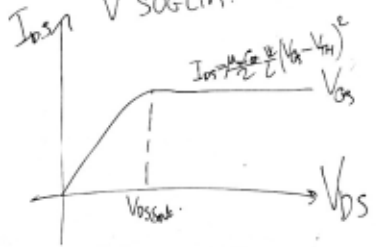


$$I_{DS} = \frac{\mu_n C_{ox} W}{2L} (V_{GS} - V_{TH})^2$$

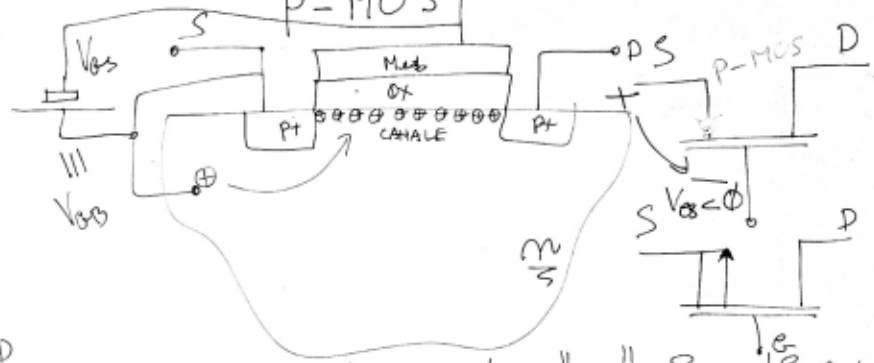
SE $V_{DS} > V_{DSsat} = V_{GS} - V_{TH}$

$$I_{DS} = f(V_{GS})$$

$V_{GS} > V_{TH}$
 $V_{THRESHOLD}$
 V_{SOGLIA}



P-MOS



$V_{GS} < \phi$ " + " Source/Subst.
 $V_{GS} < V_{TH}$
 $|V_{GS}| > |V_{TH}|$

BATTERIA
(o spina di rete)

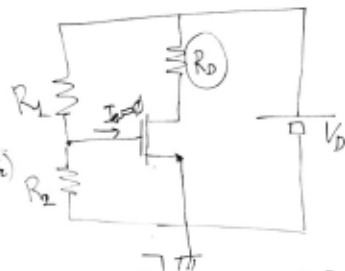
+ SEGNALE "PICCOLO"

POLARIZZ.
PUNTO di LAVORO
o di RIPOSO

LINEARIZZAZIONE

→ ESP. in SERIE di TAYLOR

VARIANZE "PICCOLE" → ... ENUTO, INFO...
delle CARATTERISTICHE
del DISPOSITIVO



POLARIZZ. del MOS.

→ SATURAZ.

$$V_{GS} > V_{TH} \quad (n\text{-MOS})$$

$$V_{DS} > V_{DSsat} = V_{GS} - V_{TH}$$

$$\rightarrow I_{DS} = \frac{\mu_n C_{ox}}{2} \frac{W}{L} (V_{GS} - V_{TH})^2$$

(BATTERIA, per il MOS $V_D = V_{DD}$)

$$V_{GS\phi} = V_D \cdot \frac{R_2}{R_1 + R_2} \quad (V_{GS\phi} > V_{TH})$$

$$\rightarrow I_{DS\phi} = \frac{\mu_n C_{ox}}{2} \frac{W}{L} (V_{GS\phi} - V_{TH})^2$$

DATO $V_{GS} > V_{TH} (R_1, R_2)$

$$\rightarrow V_{DS} < V_{GS} - V_{TH}$$

$$I_{DS} = \mu_n C_{ox} \frac{W}{L} \left[(V_{GS} - V_{TH}) V_{DS} - \frac{V_{DS}^2}{2} \right]$$

SE $V_{DS} > V_{DSsat} = V_{GS} - V_{TH}$

$$I_{DS} = I_{DSsat} = \frac{\mu_n C_{ox}}{2} \frac{W}{L} (V_{GS} - V_{TH})^2$$

$$V_{DS} > 0 < V_{DSSAT} = V_{GS} - V_{TH}?$$

$$V_D = R_D I_{DS} + V_{DS}$$

$$\rightarrow V_{DS} = V_D - R_D I_{DS}$$

$$V_{GS\phi} \rightarrow I_{DS\phi} = \frac{\mu_n C_{ox}}{2} \frac{W}{L} (V_{GS\phi} - V_{TH})^2$$

→ CALC. di $V_{DS\phi}$, se con R_D : $I_{DS\phi} > I_{DS\phi, sat}$

→ $V_{GS\phi}$, $I_{DS\phi}$ e $V_{DS\phi} > V_{GS\phi} - V_{TH}$
(R_D, R, V_D) → POLARIZZ.

POLARIZZ. del MOS.
→ SATURAZ.

$$V_{GS} > V_{TH} \quad (n\text{-MOS})$$

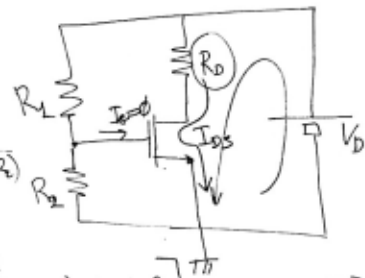
$$V_{DS} > V_{DSSAT} = V_{GS} - V_{TH}$$

$$\rightarrow I_{DS} = \frac{\mu_n C_{ox}}{2} \frac{W}{L} (V_{GS} - V_{TH})^2$$

(V BATTERIA, per il MOS $V_D = V_{DD}$)

$$V_{GS\phi} = V_D \cdot \frac{R_2}{R_1 + R_2} \quad (V_{GS\phi} > V_{TH})$$

$$\rightarrow I_{DS\phi} = \frac{\mu_n C_{ox}}{2} \frac{W}{L} (V_{GS\phi} - V_{TH})^2$$



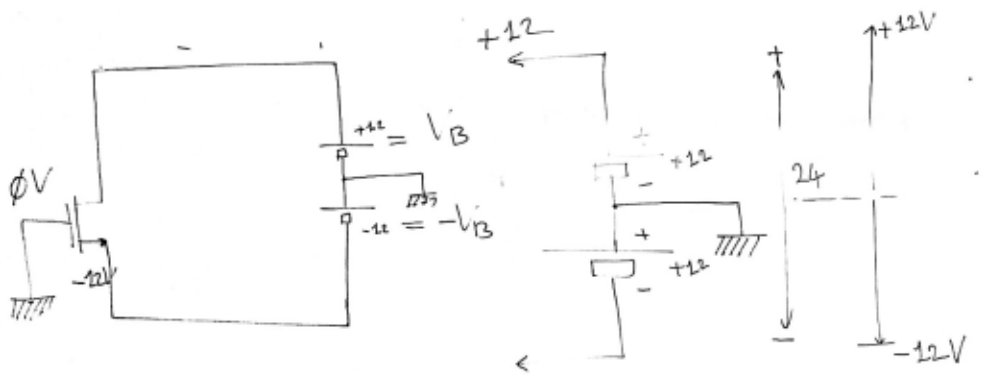
Dato $V_{GS} > V_{TH}$ (R_1, R_2)

$$\rightarrow V_{DS} < V_{GS} - V_{TH}$$

$$I_{DS} = \mu_n C_{ox} \frac{W}{L} \left[(V_{GS} - V_{TH}) V_{DS} - \frac{V_{DS}^2}{2} \right]$$

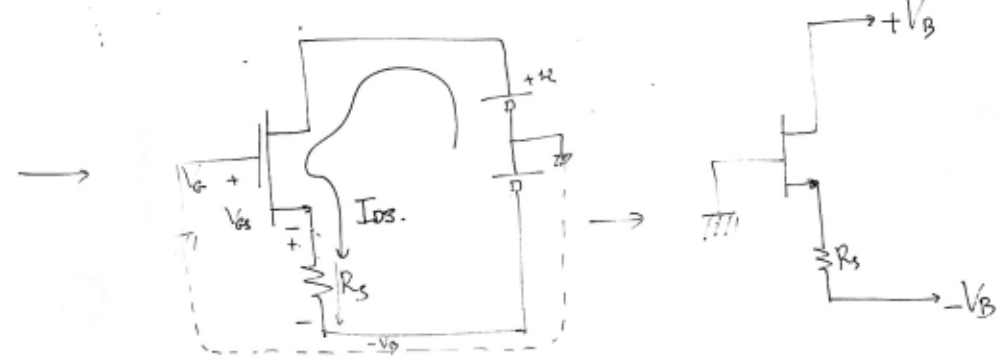
SE $V_{DS} > V_{DSSAT} = V_{GS} - V_{TH}$

$$I_{DS} = I_{DSsat} = \frac{\mu_n C_{ox}}{2} \frac{W}{L} (V_{GS\phi} - V_{TH})^2$$



$$V_{GS} = +V_B$$

ALIMENTAZIONE
DUALE



$$V_G = V_{GS} + R_S I_{DS} - V_B$$

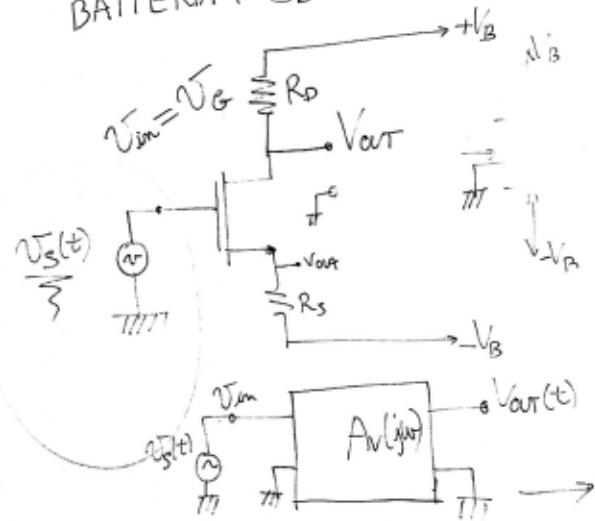
$$0 = V_{GS} + R_S I_{DS} - V_B \rightarrow$$

$$V_{GS0} = V_B - R_S I_{DS0}$$

$$V_{GS0} = V_B - R_S \left[\frac{\mu_n C_{ox} W}{2L} (V_{GS0} - V_{TH})^2 \right]$$

$V_{GS0}(V_B, R_S)$

BATTERIA + SEGNALE



$$v_s(t) = V_M \sin(\omega t + \alpha)$$

ETERA $\approx M$
 = PICCOLI SEGNALE

$$V_M \ll V_B$$

$$H(s) = \frac{v_{out}(j\omega)}{v_{in}(j\omega)}$$

$$H(j\omega)$$

$$A_v(j\omega) = \frac{v_{out}(j\omega)}{v_{in}(j\omega)}$$

BATTERIE

$$V_{GS\phi}, I_{DS\phi} (V_B, R_S, R_D)$$

$$I_{DS\phi}, V_{out\phi}$$

$$V_B = R_D I_{DS\phi} + V_{out\phi}$$

$$V_{out\phi} = V_B - R_D I_{DS\phi}$$

$$\Delta V_{out}(t) = -R_D \Delta I_{DS}(t)$$

$$V_{out}(t) = -R_D i_{DS}(t)$$

$$I_{DS}(t) = \frac{M_n C_{ox}}{2} [V_{GS}(t) - V_{TH}]^2$$

$$+ v_s(t) = V_M \sin(\omega t + \alpha)$$

SEGNALE

$$V_M \ll V_B$$

$$I_{DS}(t) = I_{DS\phi} + i_{DS}(t)$$

$$i_{DS}(t) = \Delta I_{DS}(t) = I_{DS}(t) - I_{DS\phi}$$

$$V_{out}(t) = V_B - R_D I_{DS}(t)$$

$$V_{out}(t) = V_{out}(t) - V_{out\phi} =$$

$$= V_B - R_D I_{DS}(t) - [V_B - R_D I_{DS\phi}]$$

$$= V_B - R_D I_{DS}(t) - V_B + R_D I_{DS\phi}$$

$$= -R_D (I_{DS}(t) - I_{DS\phi}) = -R_D i_{DS}(t)$$

BATTERIA + SEGNALE

$$I_{DS}(t) = I_{DS0} + \left. \frac{\partial I_{DS}}{\partial V_{GS}} \right|_{V_{GS0}} (V_{GS}(t) - V_{GS0}) + O_2$$

$I_{DS}(t)$ MOLTO "VICINA" a I_{DS}
 $\rightarrow V_{GS}(t) \ll V_B$
 $V_{TH} \ll V_B$

$$I_{DS} = f(V_{GS}(t))$$

$$I_{DS}(t) - I_{DS0} = \left. \frac{\partial I_{DS}}{\partial V_{GS}} \right|_{V_{GS0}} (V_{GS}(t) - V_{GS0})$$

$$I_{DS} = \frac{\mu_n C_{ox}}{2} \frac{W}{L} (V_{GS} - V_{TH})^2$$

$$\left. \frac{\partial I_{DS}}{\partial V_{GS}} \right|_{V_{GS0}} = \mu_n C_{ox} \frac{W}{L} (V_{GS0} - V_{TH})$$

$$f(x) = f_0 + \frac{\partial f}{\partial x} (x - x_0) + O_2$$

$$I_{DS}(V_{GS}(t)) = I_{DS0} + \left. \frac{\partial I_{DS}}{\partial V_{GS}} \right|_{V_{GS0}} (V_{GS}(t) - V_{GS0})$$

$$\left. \frac{\partial I_{DS}}{\partial V_{GS}} \right|_{V_{GS0}} = \mu_n C_{ox} \frac{W}{L} (V_{GS0} - V_{TH}) = g_m$$

$$I_{DS}(t) - I_{DS0} = g_m (V_{GS}(t) - V_{GS0})$$

$$i_{DS}(t) = g_m v_{GS}(t)$$

$$\Delta V_{out}(t) = -R_D \Delta I_{DS}(t)$$

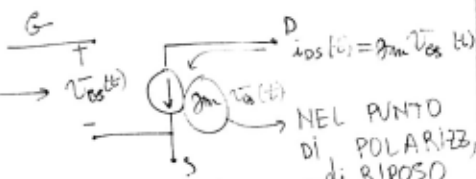
$$v_{out}(t) = -R_D i_{DS}(t)$$

$$I_{DS}(t) = \frac{\mu_n C_{ox}}{2} \left[V_{GS}(t) - V_{TH} \right]^2$$

$$\uparrow V_{GS}(t)$$

$$V_{GS}(t) = V_{GS0} + v_{GS}(t)$$

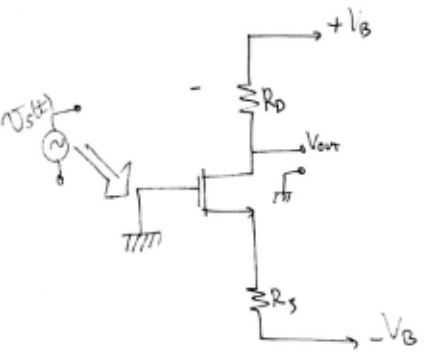
MOS LINEARIZZATO
 in $V_{GS0}, I_{DS0} \rightarrow g_m = \mu_n C_{ox} \frac{W}{L} (V_{GS0} - V_{TH})$



NEL PUNTO DI POLARIZZ. o di RIPOSO
 (V_B, R_S, R_D)

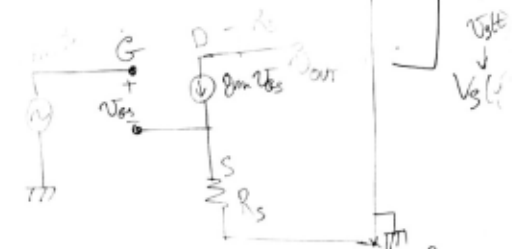


g_m : PARAMETRO LINEARIZZ.
 PARAMETRO DIFF.
 PARAMETRO per PICCOLO SEGNALE

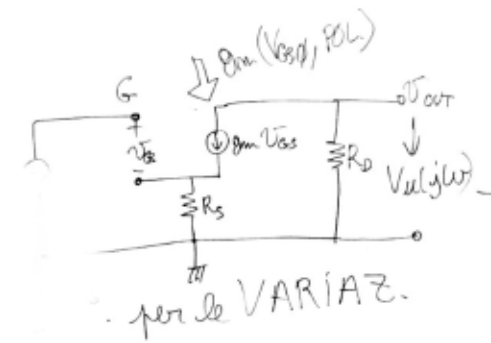


$V_S = 0$
 BATTERIE: POLARIZZ.
 $\rightarrow V_{GS0}, I_{DS0}, V_{DS0}, V_{OUT0}$

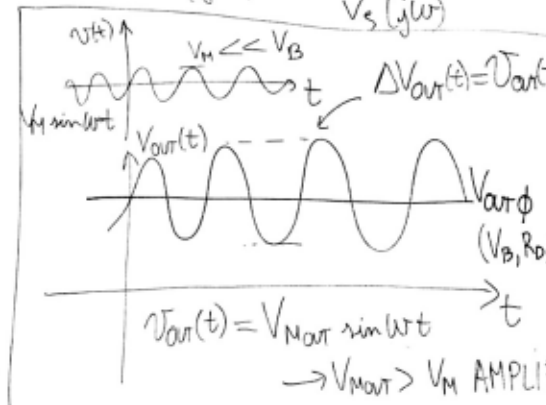
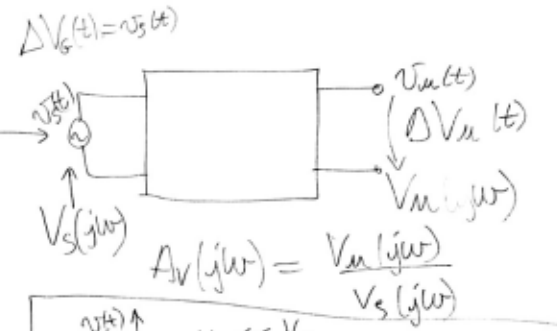
$\Delta V_{GS}(t), \Delta I_{DS}(t), \Delta V_{OUT}(t)$
 $V_{GS}(t), I_{DS}(t), V_{OUT}(t)$
 $\Delta V_{DS}(t) = \phi, V_{DS}(t) = \phi$



PARAMETRI DIFF.
 $g_m = \mu_n C_{ox} \frac{W}{L} (V_{GS0} - V_{TH})$
 NEL PUNTO di POLARIZZ.
 CIRCUITO per le VARIANZI



per le VARIANZI.
 $\Delta V_{OUT}(t) = -R_D \Delta I_{DS}(t)$
 $V_{OUT}(t) = -R_D i_{DS}(t)$
 $I_{DS}(t) = \frac{\mu_n C_{ox}}{2} [V_{GS}(t) - V_{TH}]^2$
 $V_{GS}(t) = V_{GS0} + v_{GS}(t)$



$$V_{out}(j\omega) = -g_m V_{gs}(j\omega) \cdot R_D$$

$$A_v(j\omega) = -\frac{g_m}{1+g_m R_S} \cdot R_D$$

$$V_S(j\omega) = V_{gs} + R_S I_{gs}(j\omega)$$

$$V_S(j\omega) = V_{gs} + R_S g_m V_{gs}$$

$$V_S = V_{gs} (1 + g_m R_S)$$

$$V_{gs} = \frac{V_S}{1 + R_S g_m}$$

$$V_{out} = -g_m V_{gs} R_D$$

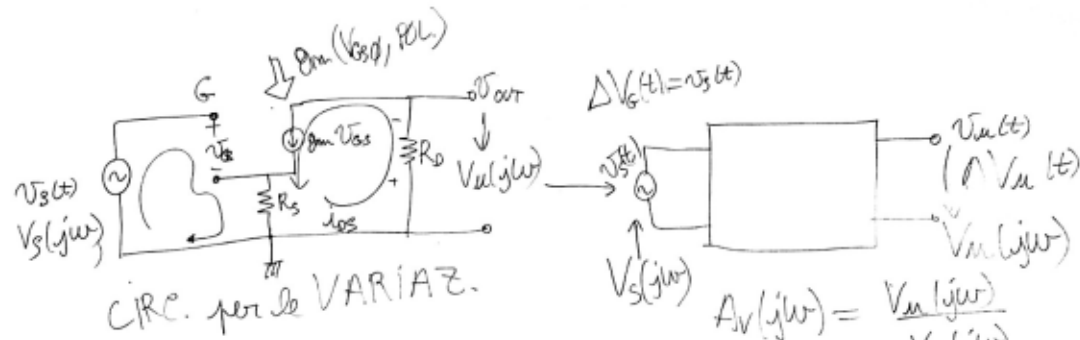
$$V_{out} = -g_m \frac{V_S}{1 + g_m R_S} \cdot R_D$$

$$A_v(j\omega) = \frac{V_{out}(j\omega)}{V_S(j\omega)} = -\frac{g_m}{1 + g_m R_S} \cdot R_D$$

(H(j\omega))

Si $R_S \gg 1/g_m$

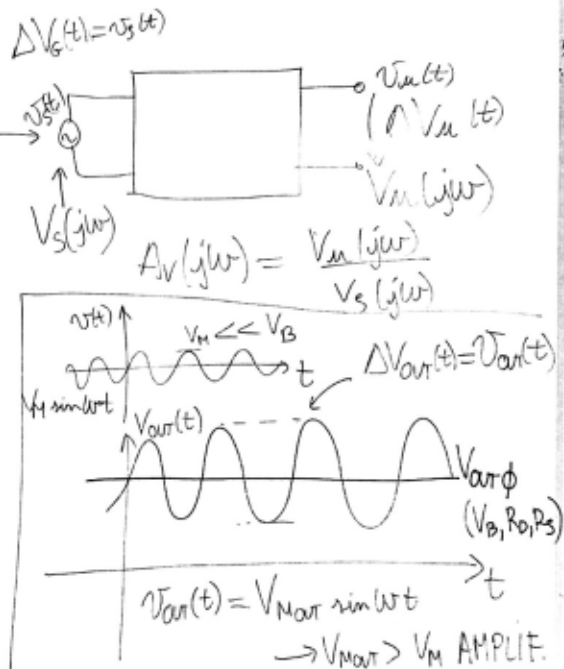
$$A_v \approx -\frac{g_m R_D}{g_m R_S} = -\frac{R_D}{R_S}$$



$$A_v(j\omega) = \cos(\omega t) = \frac{V_{MOUT}}{V_{Ming}}$$

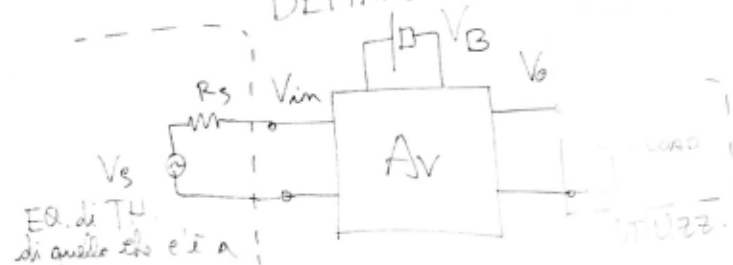
ing $v_S(t) = V_M \sin \omega t$

usc. $\Delta v_{out}(t) = V_{MOUT} \sin \omega t$



AMPLIF. di TENSIONE

DEFINIZIONE



$$V_{out} = A_v V_{in}$$

$$\left(\frac{V_{out}}{V_{in}} \right) \approx R_L \approx 816 \Omega$$

1) V_{out} PROP. a V_{in}

2) A_v MOM dipende da (V_s, R_s) e da R_L in uscita.

P_{in} , se $R_{in} = \infty$ $P_{in} = V_{in} \cdot I_{in} = 0$

se $R_{out} = \phi$

$P_{out} = \frac{(A_v \cdot V_{in})^2}{R_L}$ GRANDE se R_L piccola

$$V_{out} = A_v V_{in} \cdot \frac{R_L}{R_{out} + R_L}$$

$\rightarrow P_{out} \gg P_{in}$



$R_{in} \rightarrow +\infty$

$R_{out} \rightarrow \phi$

SE $R_{in} \gg R_s$ ($R_{in} \rightarrow +\infty$)

E $R_{out} \ll R_L$ ($R_{out} \rightarrow \phi$)

$$\rightarrow A_v = A_{v0} \neq R_s \text{ e } R_L$$

$$V_{out} = A_{v0} V_s \cdot \frac{R_{in}}{R_s + R_{in}} \cdot \frac{R_L}{R_{out} + R_L}$$

$$V_{out} = A_{v0} \frac{R_{in}}{R_s + R_{in}} \cdot \frac{R_L}{R_{out} + R_L} \cdot V_s$$

$$A_v = \frac{V_{out}}{V_s} = A_{v0} \frac{R_{in}}{R_s + R_{in}} \cdot \frac{R_L}{R_{out} + R_L}$$