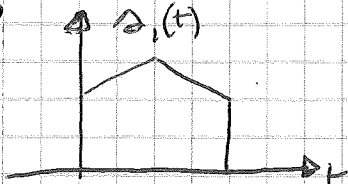


$$A = 2V$$

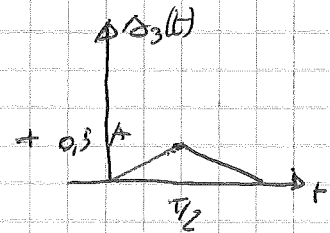
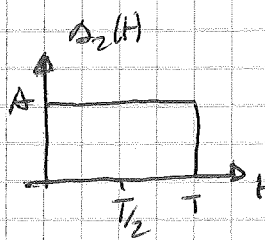
$$T = 1/2$$

posso vedere $s(t)$ come $s(t) = s_1(t) - s_1(t-T)$

con



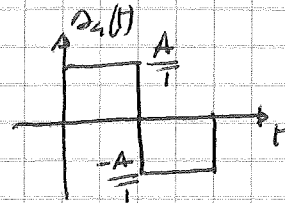
inoltre $s_1(t) = s_2(t) + s_3(t)$



$$S_2(j) = AT \operatorname{sinc}(jT) e^{-j\pi jT}$$

$$S_3(j) = \frac{S_4(j)}{j2\pi j}$$

$$s_4(t) = \frac{d s_3(t)}{dt}$$



$$= \frac{1}{j2\pi j} \left(\frac{A}{T} \frac{T}{2} \operatorname{sinc}\left(j\frac{T}{2}\right) e^{-j2\pi j\frac{T}{4}} - \frac{A}{T} \frac{T}{2} \operatorname{sinc}\left(j\frac{T}{2}\right) e^{-j2\pi j\frac{3}{4}T} \right) =$$

$$= \frac{A}{2} \operatorname{sinc}\left(j\frac{T}{2}\right) \frac{1}{j2\pi j} \left(e^{-j\pi j\frac{T}{2}} - e^{-j\pi j\frac{3}{2}T} \right) =$$

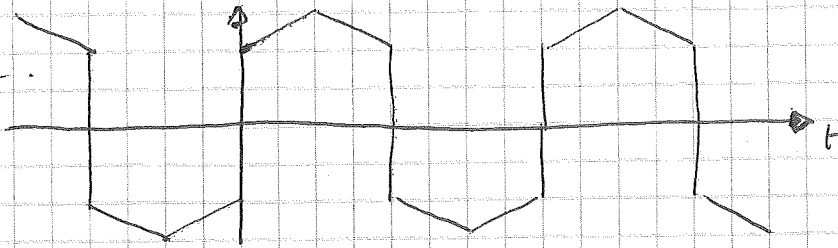
$$= \frac{A}{2} \operatorname{sinc}\left(j\frac{T}{2}\right) \frac{e^{-j\pi jT}}{j2\pi j} \left(e^{j\pi j\frac{T}{2}} - e^{-j\pi j\frac{T}{2}} \right) = \frac{A}{2} \operatorname{sinc}\left(j\frac{T}{2}\right) \frac{2j \sin(\pi j\frac{T}{2}) e^{-j\pi jT}}{j2\pi j} =$$

$$= \frac{AT}{4} \operatorname{sinc}^2\left(j\frac{T}{2}\right) e^{-j\pi jT}$$

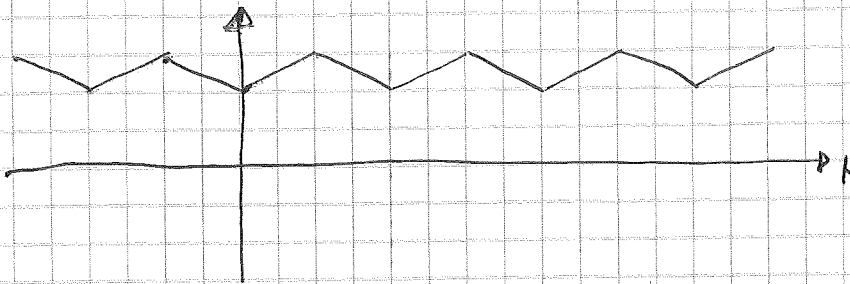
$$S_1(j) = S_2(j) + S_3(j) = \left[AT \operatorname{sinc}(jT) + \frac{AT}{4} \operatorname{sinc}^2\left(j\frac{T}{2}\right) \right] e^{-j\pi jT}$$

$$S(j) = S_1(j) - S_1(j) e^{-j2\pi jT} = \left[AT \operatorname{sinc}(jT) + \frac{AT}{4} \operatorname{sinc}^2\left(j\frac{T}{2}\right) \right] e^{-j\pi jT} 2j \sin \pi jT$$

$$i_p(t) = \text{rep}_{2T} [i(t)]$$



$$i_2(t) = |i_p(t)|$$



$i_p(t)$ è dispari $\Rightarrow S_n = -S_{-n}$ visto che è onda reale $S_n = jI_n$

l'andamento del modulo dei coeff $n \rightarrow \infty \propto \frac{1}{n}$

il periodo è $2T \Rightarrow f_n = \frac{n}{2T}$

il valore medio è nullo $S_0 = 0$

$i_2(t)$ è pari $\Rightarrow S_n = S_{-n}$ visto che è anche reale $S_n = R_n$

l'andamento del modulo dei coeff per $n \rightarrow \infty \propto \frac{1}{n^2}$

il periodo è $T \Rightarrow f_n = \frac{n}{T}$

il valore medio è diverso da 0 $S_0 = \frac{5}{4} A$

$$y(t) = x(t) + \sqrt{2} x(t-t_0) + x(t-2t_0)$$

Linearità

$$y_1(t) = x_1(t) + \sqrt{2} x_1(t-t_0) + x_1(t-2t_0)$$

$$y_2(t) = x_2(t) + \sqrt{2} x_2(t-t_0) + x_2(t-2t_0)$$

$$x_3(t) = a x_1(t) + b x_2(t)$$

$$y_3(t) = x_3(t) + \sqrt{2} x_3(t-t_0) + x_3(t-2t_0) =$$

$$= a x_1(t) + b x_2(t) + \sqrt{2} a x_1(t-t_0) + \sqrt{2} b x_2(t-t_0) + a x_1(t-2t_0) + b x_2(t-2t_0) =$$

$$= a (x_1(t) + \sqrt{2} x_1(t-t_0) + x_1(t-2t_0)) + b (x_2(t) + \sqrt{2} x_2(t-t_0) + x_2(t-2t_0)) =$$

$$= a y_1(t) + b y_2(t) \Rightarrow \text{Lineare}$$

tempo invarianza

$$x_1(t) = x(t-t_A)$$

$$y_1(t) = x_1(t) + \sqrt{2} x_1(t-t_0) + x_1(t-2t_0) = x(t-t_A) + \sqrt{2} x(t-t_A-t_0) + x(t-2t_0-t_A)$$

questo è uguale a $y(t-t_A) \Rightarrow T_0$ invariante

$$Y(j) = \bar{X}(j) + \sqrt{2} \bar{X}(j) e^{-j2\pi j t_0} + \bar{X}(j) e^{-j4\pi j t_0} =$$

$$= \bar{X}(j) (1 + \sqrt{2} e^{-j2\pi j t_0} + e^{-j4\pi j t_0})$$

$$H(j) = \frac{Y(j)}{\bar{X}(j)} = \frac{1 + \sqrt{2} e^{-j2\pi j t_0} + e^{-j4\pi j t_0}}{e^{-j2\pi j t_0}} = e^{-j2\pi j t_0} (e^{j2\pi j t_0} + \sqrt{2} + e^{-j2\pi j t_0}) =$$

$$= e^{-j2\pi j t_0} (\sqrt{2} + 2 \cos(2\pi j t_0))$$

$$|H(j)| = |\sqrt{2} + 2 \cos 2\pi j t_0|$$

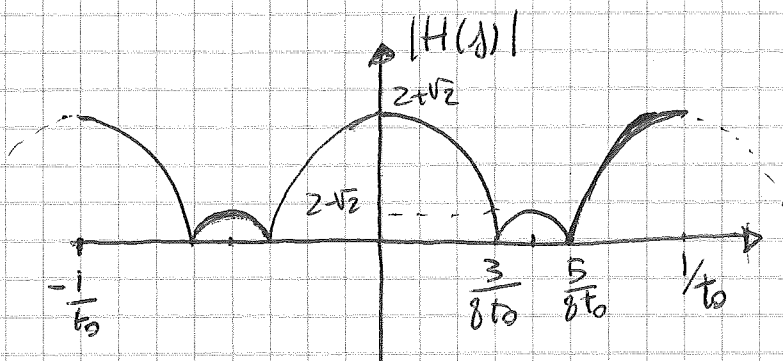
il modulo si annulla per

$$\cos 2\pi j t_0 = -\frac{\sqrt{2}}{2}$$

$$2\pi j t_0 = \begin{cases} \frac{3}{4}\pi + 2K\pi \\ \frac{5}{4}\pi + 2K\pi \end{cases}$$

$$f_{1,K} = \frac{3}{8t_0} + \frac{K}{t_0}$$

$$f_{2,K} = \frac{5}{8t_0} + \frac{K}{t_0}$$



$$x(t) = \sin\left(\frac{3\pi t}{4t_0}\right) + \cos\left(\frac{\pi t}{t_0}\right)$$

$$\tilde{X}(j) = \frac{1}{2j} \delta\left(j - \frac{3}{8t_0}\right) - \frac{1}{2j} \delta\left(j + \frac{3}{8t_0}\right) + \frac{1}{2} \delta\left(j - \frac{1}{2t_0}\right) + \frac{1}{2} \delta\left(j + \frac{1}{2t_0}\right)$$

$$Y(j) = \frac{1}{2j} H\left(\frac{3}{8t_0}\right) \delta\left(j - \frac{3}{8t_0}\right) - \frac{1}{2j} H\left(-\frac{3}{8t_0}\right) \delta\left(j + \frac{3}{8t_0}\right) + \\ + \frac{1}{2} H\left(\frac{1}{2t_0}\right) \delta\left(j - \frac{1}{2t_0}\right) + \frac{1}{2} H\left(-\frac{1}{2t_0}\right) \delta\left(j + \frac{1}{2t_0}\right)$$

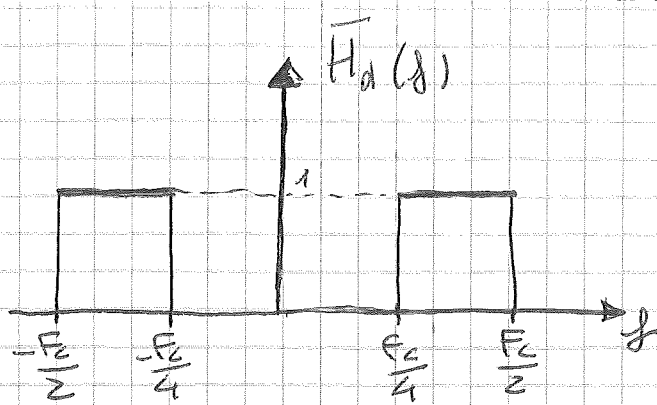
vista la simmetria coniugata di $H(j)$ per la quale $H(j) = H^*(-j)$

$$Y(j) = \frac{1}{2j} |H\left(\frac{3}{8t_0}\right)| e^{j\angle H\left(\frac{3}{8t_0}\right)} \delta\left(j - \frac{3}{8t_0}\right) - \frac{1}{2j} |H\left(\frac{3}{8t_0}\right)| e^{-j\angle H\left(\frac{3}{8t_0}\right)} \delta\left(j + \frac{3}{8t_0}\right) + \\ + \frac{1}{2} |H\left(\frac{1}{2t_0}\right)| e^{j\angle H\left(\frac{1}{2t_0}\right)} \delta\left(j - \frac{1}{2t_0}\right) + \frac{1}{2} |H\left(\frac{1}{2t_0}\right)| e^{-j\angle H\left(\frac{1}{2t_0}\right)} \delta\left(j + \frac{1}{2t_0}\right)$$

$$y(t) = |H\left(\frac{3}{8t_0}\right)| \sin\left(\frac{3\pi t}{4t_0} + \angle H\left(\frac{3}{8t_0}\right)\right) + |H\left(\frac{1}{2t_0}\right)| \cos\left(\frac{\pi t}{t_0} + \angle H\left(\frac{1}{2t_0}\right)\right)$$

visto che $|H\left(\frac{3}{8t_0}\right)| = 0$ e $H\left(\frac{1}{2t_0}\right) = (\sqrt{2}-2)e^{-j\pi} = 2-\sqrt{2}$

$$y(t) = (2-\sqrt{2}) \cos\left(\frac{\pi t}{t_0}\right)$$



$H_d(f)$ Risposta in Freq. desiderata

anti trasformo per trovare $h_d[n]$ risp. imp.

$$\begin{aligned}
 h_d[n] &= T_c \int_{-\frac{f_c}{2}}^{\frac{f_c}{2}} H_d(f) e^{j2\pi n f T_c} df = \\
 &= T_c \int_{-\frac{f_c}{2}}^{-\frac{f_c}{4}} e^{j2\pi n f T_c} df + T_c \int_{\frac{f_c}{4}}^{\frac{f_c}{2}} e^{j2\pi n f T_c} df = \\
 &= \frac{T_c}{j2\pi n T_c} e^{j2\pi n f T_c} \Big|_{-\frac{f_c}{2}}^{-\frac{f_c}{4}} + \frac{T_c}{j2\pi n T_c} e^{j2\pi n f T_c} \Big|_{\frac{f_c}{4}}^{\frac{f_c}{2}} = \\
 &= \frac{e^{-j\frac{\pi n}{2}} - e^{-j\pi n}}{j2\pi n} + \frac{e^{j\pi n} - e^{j\frac{\pi n}{2}}}{j2\pi n} = \\
 &= \frac{2j \sin \frac{\pi n}{2}}{2j\pi n} - \frac{2j \sin \frac{\pi n}{2}}{2j\pi n} = \text{sinc}(n) - \frac{1}{2} \text{sinc}\left(\frac{n}{2}\right)
 \end{aligned}$$

Per ottenere un filtro FIR causale bisogna troncare, in modo simmetrico rispetto a $n=0$ in modo da garantire fase lineare, e traslare il filtro FIR avrà $2M+1$ campioni, per cui

$$h[n] = \text{sinc}(n-M) - \frac{1}{2} \text{sinc}\left(\frac{n-M}{2}\right) \quad \text{per } n=0,1,2,\dots,2M$$

$$y(t) = x(t) - \frac{1}{2\pi} \frac{d}{dt} y(t)$$

trasf. ingresso-uscita di un sistema LTI

$x(t)$ è l'ingresso

Calcolare la risp. in Frequenza

- un modo consiste nel definire $H(j) = \frac{Y(j)}{X(j)}$

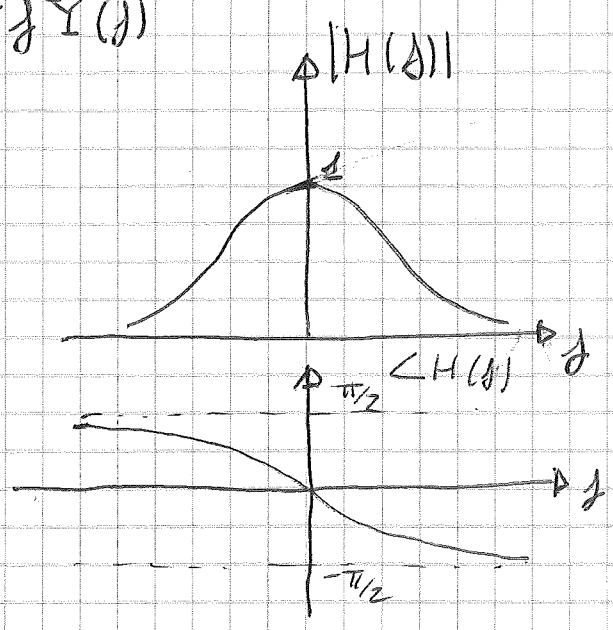
applico la TCF ad entrambi i membri dell'equazione

$$Y(j) = X(j) - \frac{1}{2\pi} j 2\pi j Y(j)$$

$$H(j) = \frac{Y(j)}{X(j)} = \frac{1}{1+j}$$

$$|H(j)| = \frac{1}{\sqrt{1+j^2}}$$

$$\angle H(j) = -\arctan(j)$$



Se in ingresso abbiamo

$$x(t) = 1 + \sin(10\pi t)$$

è fatto la repr. in Frequenza

$$X(j) = \delta(j) + \frac{1}{2j} \delta(j-5) - \frac{1}{2j} \delta(j+5)$$

allora $Y(j) = H(j) X(j) =$

$$= H(j) \left[\delta(j) + \frac{1}{2j} \delta(j-5) - \frac{1}{2j} \delta(j+5) \right] =$$

$$= H(0) \delta(j) + \frac{H(5)}{2j} \delta(j-5) - \frac{H(-5)}{2j} \delta(j+5) =$$

sapendo che il sistema è reale e quindi $H(j) = H^*(-j)$

possa scrivere

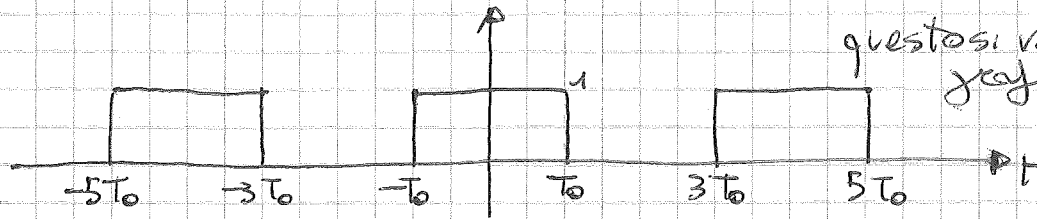
$$= H(0) \delta(j) + \frac{H(5)}{2j} \delta(j-5) - \frac{H^*(5)}{2j} \delta(j+5) =$$

$$= H(0) \delta(j) + \frac{|H(5)|}{2j} e^{j\angle H(5)} \delta(j-5) - \frac{|H(5)|}{2j} e^{-j\angle H(5)} \delta(j+5)$$

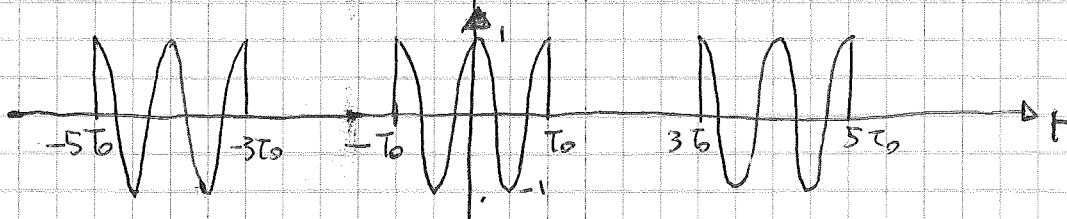
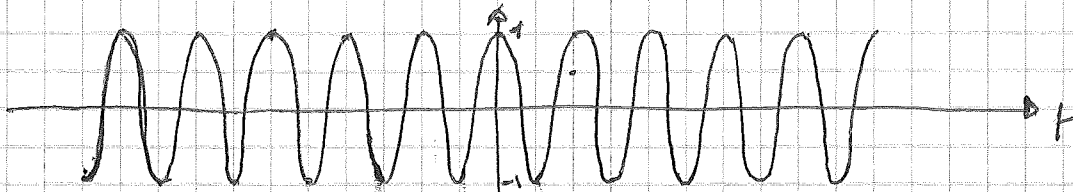
da cui antitrasformando $y(t) = 1 + |H(5)| \sin(10\pi t + \angle H(5)) =$

$$= 1 + \frac{1}{\sqrt{26}} \sin(10\pi t - \arctan(5))$$

$$x(t) = \cos \frac{2\pi t}{T_0} \sum_{k=-\infty}^{\infty} \text{rect} \left(\frac{t - 4kT_0}{2T_0} \right) \quad \leftarrow \text{è periodico di periodo } 4T_0$$



questo si vede bene dai grafici



un modo per trovare i coeff. dello sviluppo di $x(t)$ è partire dalla TCF del segnale aperiodico

$$x_1(t) = \cos \frac{2\pi t}{T_0} \text{rect} \left(\frac{t}{2T_0} \right)$$

$$\begin{aligned} S_1(f) &= 2T_0 \text{sinc}(2T_0 f) \otimes \frac{\delta(f - f_0) + \delta(f + f_0)}{2} \\ &= \frac{2T_0}{2} \text{sinc}(2T_0(f - f_0)) + \frac{2T_0}{2} \text{sinc}(2T_0(f + f_0)) = \\ &= T_0 \text{sinc}(2T_0 f - 2) + T_0 \text{sinc}(2T_0 f + 2) \end{aligned}$$

i coeff. dello sviluppo di $x(t)$ si trovano così

$$S_n = \frac{1}{4T_0} S_1 \left(\frac{n}{4T_0} \right)$$

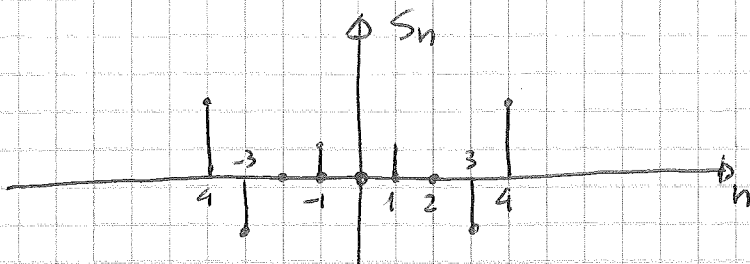
$$S_n = \frac{1}{4} \text{sinc} \left(\frac{n}{2} - 2 \right) + \frac{1}{4} \text{sinc} \left(\frac{n}{2} + 2 \right)$$

$$S_1 = \frac{1}{4} \text{sinc} \left(-\frac{3}{2} \right) + \frac{1}{4} \text{sinc} \left(\frac{5}{2} \right) = \frac{1}{4} \left(\frac{2}{3\pi} + \frac{2}{5\pi} \right) = -0,0849 \quad \Rightarrow S_{-1} = S_1$$

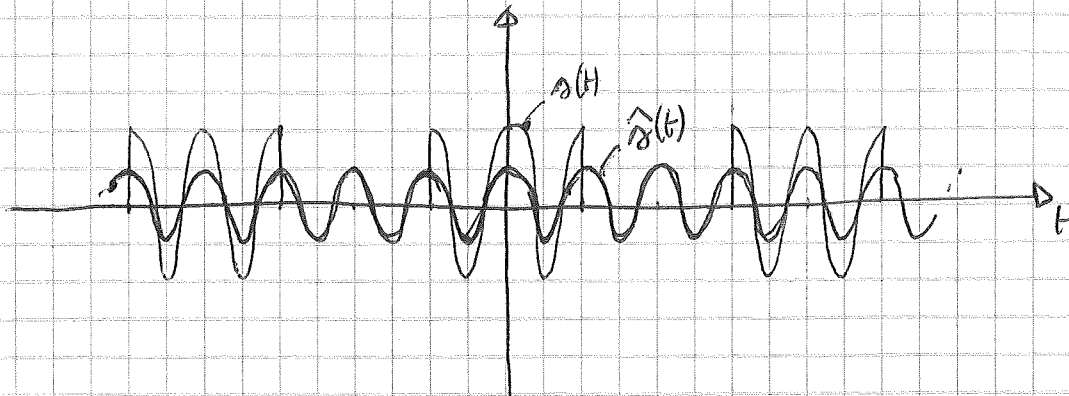
$$S_2 = \frac{1}{4} \text{sinc}(-1) + \frac{1}{4} \text{sinc}(3) = 0 \quad \Rightarrow S_{-2} = S_2$$

$$S_3 = \frac{1}{4} \text{sinc} \left(-\frac{1}{2} \right) + \frac{1}{4} \text{sinc} \left(\frac{7}{2} \right) = \frac{1}{4} \left(\frac{2}{\pi} + \frac{2}{7\pi} \right) = 0,1364 \quad \Rightarrow S_{-3} = -0,1364$$

$$S_4 = \frac{1}{4} \text{sinc}(0) + \frac{1}{4} \text{sinc}(8) = \frac{1}{4} \quad \Rightarrow S_{-4} = \frac{1}{4}$$



$$\hat{s}(t) = S_4 e^{j \frac{8\pi t}{4T_0}} + S_{-4} e^{-j \frac{8\pi t}{4T_0}} = \frac{1}{2} \cos \frac{8\pi t}{4T_0} = \frac{1}{2} \cos \frac{2\pi t}{T_0}$$



$$- x(t) = \sum_{k=-\infty}^{\infty} \text{rect}(t-k6) + \sum_{h=-\infty}^{\infty} S_h e^{j2\pi t \frac{h}{15}}$$

F.1

il periodo è il m.c.m. tra 6 e 15 $\Rightarrow T_0 = 30$

- Campionamento passa bene se $f_{\min} = 20$ e $f_{\max} = 42$ Hz

$$B = 22 \quad m = \left\lfloor \frac{f_{\max}}{B} \right\rfloor = \left\lfloor \frac{42}{22} \right\rfloor = 1$$

$$F_c = \frac{2f_{\max}}{m} = 84 \text{ Hz}$$

$$- x(t) = 1 + \sin\left(\frac{\pi}{5}t\right) + \sin\left(\frac{\pi}{6}t\right)$$

max tempo di campionamento?

$$f_{\max} = \frac{1}{t_c} \quad (f_{\min} = 0)$$

$$F_c \geq 2f_{\max} \quad t_c \leq \frac{1}{2f_{\max}} = 5$$

$$- x[n] = [u[n] - u[n-2]] \otimes \sum_{h=-\infty}^{\infty} \delta[n-h6] \quad \tilde{x}_1 = ?$$

$$\tilde{x}_k = \frac{1}{6} \sum_{n=0}^5 x[n] e^{-j2\pi nk/6} = \frac{1}{6} [1 + e^{-j2\pi k/6}]$$

$$\tilde{x}_1 = \frac{1}{6} [1 + e^{-j2\pi/6}] = \frac{1}{6} [1 + \cos\frac{\pi}{3} - j \sin\frac{\pi}{3}] = \frac{1}{6} \left[\frac{3}{2} - j \frac{\sqrt{3}}{2} \right] =$$

$$= \frac{1}{4} - j \frac{1}{4\sqrt{3}}$$